

micro:bit A STARTER GUIDE OF BOSON KIT



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Chapter 1: Mind+ and micro: bit



Really? Great! Let's begin our programming with Mind+ and micro: bit!

1. Introduction to Mind+

With so many different graphical Programming software products on the market, how can you get the right one? It may disappoint you when you found that your software only supports some certain hardware and robots or even cannot work with any hardware at all. Where to find a software with all you wanted?

Why not try our Mind+ graphical Programming software!

Mind+ is a graphical Programming platform that can support all kinds of open source hardware such as Arduino, micro: bit. It is not only suitable for primary and secondary school students, but also able to provide a great learning environment for makers who want to improve themselves by studying high-level Programming language such as Arduino, python, c, c++ etc. Drag and combine code blocks to make programs, easy to find the joy of creating.

From beginners to experienced makers, Mind+ can satisfy all your needs: learning Programming, running programs without downloading, experiencing IoT(Internet of Things), sharing ideas with Mind+ community and so on.

Come and play with Mind+, more surprises waiting for you!

1.1 Download and Install Mind+

STEP1: Download Mind+ Programming Software (The tutorial is based on Mind+ V1.1.2)

Open the webpage and download: http://mindplus.cc



Figure 1.1.1 Mind+ Download Interface

STEP2: Install Driver

After downloaded and installed the software, open and click "Learning" to learn how to install driver.

1. Click to open Learning ->Video Tutorials.



Figure 1.1.2 Video Tutorials

2. Click the related tutorial, and play the video.



Figure 1.1.3 Click to play the video

3. Install the SerialPort driver according to the instruction.

And you just need to install the driver for once.

🚔 Minda Project 🗸 Learning 🗸	Connect device 👻	⑦ Feedback Scratch Code 💿
Blocks	Connect device	Jpload arduino C 🔻
Control	Install SerialPort Driver	Generate Manual Editing
wait 1 secs	23	void setup() { }
Operators Variables	stall the Serial	Port Driver
My if then		

1.1.4 Install SerialPort Driver

STEP3: Switch to "Code" mode (The tutorial is based on "Code" mode).

- 1. Click "Code" icon at the right corner to switch mode.
- 2. Switched to "Code" mode successfully.



Figure 1.1.5 Switching mode



Mr. Micko, what's the difference between these 2 modes?

My little friend, the mode Scratch will execute script programs in hardware and Mind+ stage in real time. But the mode Code will upload programs to hardware devices first then execute.



1.2 Mind+ Interface

To convenient the operation, first we should be familiar with the basic functions of the software's interface. If we compare the Mind+ software as a stage, what are the functions of its different sections?

∭ M	Project 🗸		Menu Bo	Version Update	? Feedback Scratch Code
Block	s				Upload arduino C
	Control	1.1			Auto Generate Manual Editing
Control	wait 1 secs				1 • void setup() { 2 }
perator	repeat 10				3 4 • void loop() { 5
oriables	,				7
	then then	1 A 1	 		Code
My Blocks			 Script	· · · · · · · ·	
	if then		 	.	
	else				Serial Port
Co	ommana				
	wait until				
Extensions	repeat until	1.1	 <u></u>		∲ ∦

Figure 1.2.1 Mind+ Interface

Menu Bar: Software setting area.

This is the backstage of the whole "stage". Without the help of the menu bar, we can do nothing with this software. What functions are there behind the "stage"?

"Project": create a new project, load a project, save a project, save a project as.

"Learning": where you can find lots of useful tutorials and examples programs.

"Connect Device": detect the connected device, and you can select to connect or disconnect the device.

"Scratch/Code" icon: switch mode to run program.

"Setting" icon: set the theme and language of the software; share and learn on our community or E-mail us your feedback.

Command: This is the "tool section" of the stage. We need all kinds of tools to give an excellent performance on the stage, and we can get more extra tools in "Extensions" to support different hardware.

Script: Here is the core of the "stage performance". All performances will be acted under the instruction of "script". This is what we called graphical Programming, easy and simple for beginners to understand. Just drag the code blocks in the "Command" to here then you can program.

Code: If you want to check the codes of the blocks in the "script", this is the right place.

Serial Port: How do you know whether you have made a successful performance? -Interact with your audience. This is the place your audiences give you their "opinion" about the performance. The downloading situation will be displayed on there, so you can check whether your download is successful, or if not, what's the reason. Besides, you can see the programs running here. The serial port communication data will also be displayed. That is to say, if your micro: bit board is connected with an external sound sensor, you can find the related data here. This section also includes: serialport open/close, scroll display open/close, clear output, baud setting, serialport input and output format control.

2. Micro: bit

Micro: bit is an open source hardware ARM-based embedded system designed by the BBC. It has accelerometer, magnetometer, Bluetooth, three buttons and a display consisting of 25 LEDs.

With micro: bit, you can create many interesting and cool things, for example, use it as a mini-mobile phone; connect the board with phone through onboard Bluetooth, then send commands to control the board by the phone; realize telecommunication of multiple micro: bit boards via wireless connection to finish tasks requiring long-distance control; use magnetometer to make navigation device....

Micro: bit is equipped with light and temperature sensors and other common sensing devices, which means that it itself can produce a lot of common smart products used in our daily life.



Figure 1.2.1 Front of micro: bit



Figure 1.2.2 Back of micro: bit

micro: bit and micro: bit Expansion Board

Limitation of micro: bit

1. micro: bit cannot directly drive devices requiring large currents like, motor, servo etc. due to its poor drive ability, so edge connectors are necessary for connecting more external devices.

2. The power supply and signal voltage of micro: bit is 3.3V, which cannot work together with the common 5V electronic components.

The advantages of micro: bit expansion board

1. micro: bit expansion board can easily lead out the extra pins of micro: bit, plug and play, easy to use;

2. The expansion interfaces of micro: bit improve the safety and stability of connection.

3. Micro- USB external power port VIN can be used to provide extra power for external electronic devices such as LED strip, servo etc. (USB wire still needs to be connected to micro: bit when running the programs.)

4. Micro: bit expansion board comes with 3.5mm headphone jack and volume knob, supporting direct connection of headphone.



Figure 1.2.3 micro: bit expansion board

The maximum rated current of micro: bit expansion board is 500mA. Please confirm the max power of your component. Do not use the expansion board together with high-power servo, otherwise on-board units damage may occur.

3. Get Started with Mind+ and micro: bit

Please prepare a Windows computer and components as below before we get started:



Figure 1.3.1 micro: bit



Figure 1.3.2 micro USB connector

STEP1: Select micro: bit

1. Click "Project"-> "New Project" at the upper-left corner.

ÊM	indt	Project 👻	Learnin	g 🔻	C	onn	ect	de	vice	-			1	Ð١	/ers	ion	Upd
Block	s	New Proje	ct														
		Load Proje	ect														
Control	Control	Save Proje	ct														
	wait 1	Save As															
Operators		10															
	repeat	10															

1.3.3 Create a new project

- 2. (1) Click "Extensions" at the lower-left corner
 - (2) Click "Board"
 - (3) Click "Micro: bit"









STEP2: Edit a simple program

Edit a program to display a pattern on micro: bit LED panel:

1. Drag the blocks we do not need currently to "command area" to remove it.

Block	s
	micro:bit
Control	
Operators	• when button A • pressed
Variables	when micro: bit pin P0 + constants and the micro: bit starts
My Blocks	when logo up Tonever 1 Drag the blocks we do not need currently
iii micro:bit	to "command area" to remove it.
	e display built-in pattern and a display built-in pattern and

Figure 1.3.6 Remove Blocks

2. Click "micro: bit" module



Figure 1.3.7 Click "micro: bit" module

- 3. Drag "display pattern" block onto "Script" area.
- 4. Place "display pattern" block under the "micro: bit starts" block





STEP3: Upload to device

1. Connect micro: bit board to your computer via USB, then the power indicator on the board will light up.



Figure 1.3.9 Connect micro: bit to computer

- 2. Click "Connect Device" in the menu bar, then click "COM-micro: bit" in the drop-down menu to connect micro: bit board to the computer.
- 3. When connected, edit your programs and click "Upload" to upload the programs to your board (if the connection fails, then it will prompt "No Device Connected". There will be a prompt box to display the uploading progress. When the program is updated, the prompt box will disappear.



Figure 1.3.10 Run the program

micro: bit power indicator flashes only when uploading the program, and stops flashing and keeps ON after the upload is completed.

Try uploading a program to your micro: bit board, and make the board display an "love heart" for you!





The basic usages of micro: bit was shown above. If you have any quires, please feel free to contact us on our forum at https://www.dfrobot.com/forum/

Welcome to our DFRobot Community to find more tutorials and fantastic projects, and of course you can also share your own projects or ideas on our community. Looking forward to your log in!

How do you feel about these learning? Have you improved yourself?



Of course! Mr. DFRobot, now I have a basic knowledge about Mind+ and micro: bit.

And I can make a red heart!

You are so smart! This is just a begin, we will get to know more about Mind+ and micro: bit in future. And you can use them to do what you want.



Micko

Awesome! I will try my best. Mr. Micko, please teach me.

Chapter 2: What Makes a Machine "Come to Life"

After reading the previous introduction, are you itch to have a try? Now, let's begin our journey with micro: bit!

Project 1: The Mysterious micro: bit

1.Story of Cat and Micko



2.Micko's Pocket





1 × micro USB Cable

All necessary components are in the pocket of Micko.

3.Dream of Cat



4. Micko's Blackboard

STEP1: Connect micro: bit to your computer via USB cable.



Figure 2.1.1Connect micro: bit to Computer

STEP2: Programming

1) Open Mind+ software, click Project->New Project, and then select "micro: bit"



2) Click "micro: bit" at the left side of command area, and find "micro: bit starts" block, which is very necessary for editing your program.



Figure 2.1.2 micro: bit starts

3) Drag "forever" block to the left to delete it.



Figure 2.1.2 Delete Blocks



4) Click micro: bit module, and find "display pattern" block. Drag the block to script area and place it under "micro: bit starts" block.



Figure 2.1.3 Drag Blocks

5) Click the black square in the "display pattern" block we dragged to script area, then we can start to design our own pattern. First, let's make a super cute "love heart".



Figure 2.1.4 Design a heart pattern

6) Click "Upload" to upload the program to micro: bit board. Then, you will find a "heart" on micro: bit LED panel.



Remember to connect the device before you "Upload": Click "Connect Device" in the menu bar, then click "COM-Micro bit" in the drop-down menu to connect micro: bit board to the computer.

5. Design of Cat

Try making one virtual pet, imaging what it looks like?



Look Design	Program Design
- The second sec	

Project2: Flash the LED Light

1. Story of Cat and Micko



Mr. Micko, the lovely little heart made last week is very interesting, my classmates love it!

> My dear, not just emojis, playing mind+ and micro: bit can make as much as you can imagine.





Really?! Mr DFRobot, colorful lights are my favorite things. Could I bring them home?



It's my pleasure to teach a student who is fond of learning. Okay, let's welcome a new friend-LED lights.





Fantastic! Let's do it now!

2.Micko' Pocket



1 × micro: bit



1 × micro: bit Expansion Board



1 × LED Module



1× micro USB Cable

3.Dream of Cat: Light up LEDs



4. Micko's Blackboard

STEP1: Connect micro: bit board to micro: bit expansion board.



Figure 2.2.1 Connection Method



Figure 2.2.2 Connection Diagram

Note: the following projects we will learn are based on the combined

use of micro: bit board and micro: bit expansion board.



Mr. Micko, Why should we use these two boards together? Could we only use the main control board micro: bit?

Well, the reason why should we use the expansion board has already explained in the introduction of micro: bit.



STEP2: Connect the LED module to pin P1 of the expansion board.



Figure 2.2.3 Connect LED

STEP3: Programming

 Open Mind+ interface, create a new project and select micro: bit board in extensions. Scroll down the "micro: bit" blocks to find "set digital pin P0 output LOW" block, drag it onto script panel. Then we need to change "P0" to "P1", "LOW" to "HIGH".





under the main program. Then "upload" the program to your device.

Block	s														
Control	the number of LEDs		1		micr	o bit	starte								
Operator	set operation direction - to 🕡			forev											
	change operation direction - b				set	digi	tal pii	n PO	•	outp	ut	HIG	н		
Variables	Create string Make a List														
My Blocks	My Blocks														
	Make a Block														
Microbit	() micro:bit starts														
display															
	when button X+ pressed														
	when microbit pin P0 • c														
	• when logo up •														
	💼 display pattern 🛄														
	💿 display built-in pattern (📶														
Extensions	display (hello world)														



3. Result: the LED will be on when the code is uploaded successfully.





5.Dream of Cat: Flash the LED Light



6.Micko's Blackboard

- The connection is same as above. Create a new project to make the LED flash.
- 2) How to flash the LED? Just let the LED repeatedly keep on for 1 second and keep off for 1 second. To achieve that effect, we need to use "wait 1 sec" block in "control" module.



Figure 2.2.7 "wait 1 sec"



Mr. Micko, I remember! Here we can use "forever" (loop) to keep execute the program.

Good memory! Yes, the loop block 'if...then' is used to execute program again and again.



3) Place "wait 1 sec" block under the "set digital pin P1 output HIGH" block so as to let the LED keep on for 1 second then do the next action.



Figure 2.2.8 Drag "wait 1 sec" Block

 Next, we need to let the LED keep off for 1 second. Right-click "set digital pin P1 output HIGH", then click "Duplicate".



Figure 2.2.9 "Duplicate" Blocks



Cool! Click the right mouse can duplicate the blocks. It is very convenient!

5) Place the duplicated blocks under the block "wait 1 sec", change "HIGH" to "LOW" to let the LED keep off for 1 second. Since we used forever statement here, the program of LED flashing will be running all the time.



Figure 2.2.10 Run the program

Result: the LED keeps flashing when the code is uploaded successfully.

7.Design of Cat

Sweetie, I heard that you will go camping with your friends. I am worrying you may get lost outside.

How about make one emergency device SOS?

Reminder: How to send emergency signal SOS via LEDs? To send out SOS for help, we just need to flash LEDs according to the rule 3 shorts, 3 longs and 3 shorts again. 3 longs are presented by 'ON---OFF---ON---OFF---ON---OFF---' and 3 shorts are presented by 'ON-OFF-ON-OFF-ON-OFF- '. Notice it? The time that 3longs costs are 3 times of 3shorts. Let's do it!



My Design	My Program	

Project 3: Notification Light

1.Story of Cat and Micko



Mr. Micko, I will flying to DF Starship with my friends this week, but I am a little afraid of dangers.



Eh, it will cost several hours at plane. You guys should prepare some emergency equipment.

Yes, Mr. Micko, if the plane goes off course and we got lost in the vast cosmos, what should we do?

> My dear, do not be frightened. Once you have be noticed by other spaceships, you will be safe.





Oh! We can make a notification light. Its brightness can be adjusted from the maximum to the minimum. If any dangers, we can adjust the light to the maximum brightness. And others can easily find us!

Mr. Micko, could you please help me make it?

No problem! Let's make one notification light.



2.Micko' Pocket



1 × micro: bit



1 × micro: bit Expansion Board



1 × LED Module



1 × Push Button



1× micro USB Cable



Know something about Push-button and Switch Knob:

Push-button is the common button we can find on lamp. By programming, we can realize to turn on/off the LED through the Push-button.

Switch the knob to different angles, we can control the brightness of the LED.

What's the differences between Push-button and Knob?

Both are input modules.

The electric circuit can only be connected when the Push Button is pressed. And the electric circuit can be connected when the Knob rotates within one range.



Mr. Micko, is that Input inputs signals?

So clever! You are right. For an example, in the project LED control via the Push Button, the Push Button is a input and the LED is a output.



3.Dream of Cat: Control LED by Push Button



4. Micko's Blackboard

STEP1: Connect Push-button module to pin P0 of the expansion board; connect the LED to pin P1.



Figure 2.3.1 Connection Diagram

STEP2: Programming

 Click "micro: bit" module, find "read digital pin P0" block and drag it to script area.







Mr. Micko, why not use high level and low level at here?

Sweetie, because we need to check the P0 value to judge whether the Push Button is pressed.

When the Push Button is pressed, the digital value read by Mind+ is 1, which means high level and the LED is ON.

Well, when the Push Button is loosen, the digital value read by mind+ is o, which means low level then the LED is OFF. So it is certain to be used in the future, but not now.



2) The "=" in the "Operators" module can be used to judge if the pushbutton is being pressed. If the value of "read digital pin P0" is "1", the button is pressed, otherwise, it is unpressed. Nest the block "read digital pin P0" into the equation.



 Find "if then...else" block in the "Control" module, and drag it into the "forever" block.



Figure 2.3.4 "If then...else" Block
4) Nest the conditions of equation into the "if then...else" block as shown below:



Figure 2.3.5 Nest Blocks

5) Find the block "set digital pin P0 output LOW" in the "micro: bit" module. Revise the block into "set digital pin P1 output HIGH" and place it under "if then" block. When the button is pressed, this command will be executed and the LED will be on. Then place "set digital pin P1 output LOW" block under the "...else" block. When the button is released, the LED will be off.



Figure 2.3.6 Run the Program



6.Micko's Blackboard

STEP1: Replace the push-button module in the last project with switch knob module.



Figure 2.3.7 Connection Diagram

STEP2: Programming

 Connect the switch knob to pin P0. Click "micro: bit" module and select "read analog pin P0" block.



Figure 2.3.8 "read analog pin PO" Block

The brightness of LED is decided by the value of the analog pin (knob's angle). Switch the knob to control the LED's brightness. Micro: bit "read analog pin" (knob) ranges from 0 to 1023, so does the output analog pin. So, it's ok to read the analog pin P0 directly!

2. Drag "read analog pin P0" to the script area.





 Drag "set analog pin P0 output" block of "micro: bit" module into "forever" block in script area, and change P0 to P1. Nest the "set analog pin P1 output" block with the block "read analog pin P0".



Figure 2.3.10 Run the Programs

We can understand the codes in this way: the value of the position the knob switched is the brightness of the LED.

40 / 115

7.Design of Cat

My dear, can you design a beautiful and practical

rotation light now?



	My Design	My Program	
	, 3		
			· · · · · · · · · · · · · · · · · · ·
125			

Project 4: Electric Fan

1.Story of Cat and Micko



42 / 115

2.Micko' Pocket



1 × micro: bit



1 × micro: bit Expansion Board



1 × Fan Module





1× micro USB Cable



The fan is similar to household fan, inside of which has motors and blades. The speed of the fan is adjustable.

3.Dream of Cat: Push-button Fan

οΟ

I want a remote-control fan so

that I can sit at sofa and

conveniently turn the fan ON



and OFF.

4. Micko's Blackboard

STEP1: Connect the push-button module to pin P0 of the expansion board; connect the fan module to pin P1.



Figure 2.4.1 Connection Diagram

Let's see how to use the fan module:

Connect micro: bit with computer, debug and download your programs.

In the experiment the power consumption of fan and servo is large, so independent power supply (USB power supply) is necessary. Connect the external power to the VIN port of the extension board.



Detect the pin value (0 or 1) to judge if the button is pressed. When it is pressed (pin value=1), the pin connected to the fan is HIGH, and the fan starts to work. When the button is released (pin value=0), the pin connected to the fan is LOW, and the fan stops rotating.

STEP2: Programming

1. Click "micro: bit" module, select "read digital pin PO", and drag it to

script	tsec	tic	n.														
	Mi	ndt															
	Blocks	;															
	Control	\bigcirc	read ambient brightness														1
		\bigcirc	read compass orientation		💿 mi	cro:bit s	starts										
	Operators	\odot	read temperature		forever												
	Variables	\odot	read acceleration x •														
		\odot	read magnetic force x •														
	My Blocks	0) read digital pin P0 -			read	digital	pin (P0 -								1
		$\overline{\mathbf{O}}$	read analog pin P0 -														
	micro:bit	\odot	set digital pin P0 🔹 outpu														
			set analog pin P0 🔹 outpu														1
				ig	jure 2	2.4.	2 ''r	e	d	di	gi	ta	Ιp	bin	"		

- 2. The "=" in the "Operators" module can be used to judge whether the
 - button is pressed. If the value of "read digital pin P0" is "1", which suggests the button is pressed, otherwise, it is released. Nest the block "read digital pin P0" into the equation.



Figure 2.4.3 "="

3. Find "if then...else" block in the "Control" module, and drag it into the

"forever"	blo	ck.												
	M	ரேஞ்சு Project												
	Block	s												
		Control												
	Control	wait 1 second	s											
	Operator	repeat 10												
					••	micro:bit	starts	10						
	Variables				forev									
	Mv	if then			if	the								
	Blocks				else									
	() microshit	if then												
	micro.bit	else												
		wait until 🌑) read	l digital p	pin PC		= (1					

Figure 2.4.4 "If then...else"

 Nest the conditions of equation into the "if then...else" block as shown below.





5. Find the block "set digital pin P0 output LOW" in the "micro: bit" module. Revise the block into "set digital pin P1 output HIGH" and place it under "if then" block. When the button is pressed, this command will be executed and the fan starts to rotate. Otherwise, the fan stops rotating.

if 🔇	read digital pin P0 -	= 1) the
	set digital pin P1 - output	HIGH 🗸
else		
\odot	set digital pin P1 • output	LOW -

Figure 2.4.6 Run the program



How observant you are! Yes, the principle to control a fan is as soma as to control a LED. It is so great that you can think and consider. Keep this good habit!



5.Dream of Cat: Set the fan running at different speed



6.Micko's Blackboard

STEP1: Replace the push-button module in the button-fan project with switch knob module.



Figure 2.4.7 Connection Diagram

STEP2: Programming

1. Click "micro: bit", drag "read analog pin P0" block to script section



Figure 2.4.8 Read analog pin P0

 Drag the "set analog pin P0 output" of the micro: bit module to the "forever" in the script area, revise P0 to P1, and nest the two blocks as shown below.



7.Design of Cat

The summer is coming, do you want to make a cool fan lamp? Then you can enjoy the cold wind more comfortable. Tip: How to use 1 micro: bit to control LED and fan at the same time?





Chapter 3: Get hands on!

Except the push-button and switch knob module we learned before, there are more commonly-used sensors. Use them to make more smarter, funnier and useful projects. Come and learn!

Project 1: Electronic Candle

1.Story of Cat and Micko



Mr. Micko, it's been a long time. We are back from the DF spaceship.

How's the traveling? Have you enjoyed yourself?



Yes, a nice trip. Here is a TV in the DF spaceship and I watched a video about greenhouse effect, and the main cause is greenhouse gas. So seriously. From the news I know any human activity may emits greenhouse gas, such as making a fire, driving car, air-conditioner.

You are right, we should try our best to protect nature, and reduce the greenhouse gas emission.



Mr. Micko, I will attend a birthday party of my best friend. What kind of gift should I give her?

How about an electronic candle? An electronic candle will not pollute the environment.







2.Micko' Pocket



1 × micro: bit



1 × micro: bit Expansion Board







- - 1 × micro USB Cable

Let's get to know about sound sensor:

Sound sensor can sense the intensity of sound. After programming, it can be used to turn on/off the LED through the sound intensity.

3.Dream of Cat: Detect the sound strength



How to design the project?

When the analog value of sound intensity is less than 80, we set the on-board LED display the figure "1", which means that the sound is low and intensity is grade 1.

Elsewise, when the analog value is over 80, the on-board LED display figure "2", which means the sound intensity is grade 2.

4. Micko's Blackboard

STEP1: Connect the sound sensor module to the pin P0 of the extension board; LED module to P1.



Figure 3.1.1 Connection Diagram

STEP2: Programming

 Let's begin to design our project according to the tips: drag "read analog pin P0" and "display" blocks from the "Micro: bit" module; drag out "if... then...else" block from the "Control" module; drag "<" in the "Operation"
module to script area.



Blocks	Operators
repeat 10	Control +
Control	
	Operator
Operators it then	
Variables	Variables
if then	pick random 1 to 10
My	My
Blocks	Blocks
microphit wait until	
repeat until	

Figure 3.1.2 "if...then...else"



- 2. Read the analog value(0~1023) of "read analog pin P0" that connected with sound sensor to detect the sound of intensity.
- 3. Edit the programs to realize "sound intensity detecting". "<" can be used to judge if the analog value of sound intensity meets the set standard.

AS shown in figure 3.1.4, if the condition "'read analog pin PO'<'80'" is true, also means the sound intensity grade is 1, the on-board LED displays figure "1".

If the condition is false, the sound intensity grades 2 and the LED displays figure"2". Add a "wait 1 sec" block under the "...then" to prevent the LED figure from flashing.



Figure 3.1.4 Run the Program

Mr. Micko, this program really can test my voice power!

Well done! If it always shows 2, suggesting the environment is a little noisy. And the value 80 is too low. So, you should try setting a larger number.



5.Dream of Cat: micro: bit Candle



6.Micko's Blackboard

Control the LED to turn on/off according to the value of the pin connected to the sound sensor. "

Let me explain the principle of this electronical candle. When we don't blow, the voice cannot reach the lowest strength, the LED is ON and the LED Pin is high level; And when we blow, the voice reaches the lowest strength. The LED is OFF and the LED Pin is low level.



1. Drag "set digital pin P0 output" block from "micro: bit" module to script area, and change P0 to P1.



Figure 3.1.5 "set digital pin output"

2. Programming to make a "electronic candle"

When the analog value of sound sensor is less than the preset value 80, the LED keeps on, otherwise, blow it like a candle, when the sound intensity is over 80, the LED keeps off for 2 seconds.



Figure 3.1.6 Run the Program



1.Story of Cat and Micko



2.Micko' Pocket



1 × micro: bit



1 × micro: bit Expansion Board



1 × Push Button



1 × Motion Sensor



1× micro USB Cable



1 × Servo

First time to see Motion sensor and servo module, let's take a look:

Motion sensor, also called PIR sensor, can detect the infrared signals from human body or other animals and triggers with movement.

A servo come with a shaft that can be positioned to specific angular (0-180°/0-360°). Compared with motor, it has smaller rotation speed but larger torque. They are extremely useful in robotics.

3.Dream of Cat: Control Servo with Push Button



4. Micko's Blackboard

STEP1: Connect push-button module to pin P0 of the expansion board; connect servo to P1.



Figure 3.2.1 Connection Diagram

Add a command module before programming:

If we want to control the servo, we have to add the servo mand module. How to do that?

Click Extensions->Actuator->Micro Servo, and then back to the former interface.





Figure 3.2.2 Extensions

Figure 3.2.3 Actuator->Micro Servo

STEP2: Programming

1. Drag "set pin P9 servo to...degree" block in "actuator" module. Change P9 to P0. Set pin P0 to control servo' s value.



Figure 3.2.4 "set pin PO servo to...degree"



Set: if the button is pressed, the servo rotates for 100 degree and the LED display "o". Otherwise, the servo rotates for 0 degree and the LED display "x". Here we need to use "if...then...else" statement.



Note: an external power supply is necessary since the power consumption of the servo is large. If you forgot how to connect the external power, review it at the "Control the fan with Push Button"

3. Run the program



Figure 3.2.6 Run the Program



Mr. Micko, this is exactly what I want! But I forgot to connect the power supply and worried that the servo maybe broken.

That's Ok, we need to be patient and careful during testing the program.



Result



Figure 3.2.7 Result-Loosen



Figure 3.2.8 Result-pressed

5.Dream of Cat: Control the Servo with Motion Sensor



6.Micko's Blackboard

STEP1: Connect the servo to pin P1; connect the motion sensor to pin P0.



Figure 3.2.9 Connection Diagram

STEP2: Programming

1. Read the digital pin P0 to get the digital signal data of the motion sensor.

ÊM	indt	Project 👻 Learnin	g 👻	Co	nne	ct De	vice								
Block	s														
	6	A - button is pressed?													
Control		P0 • pin is connected?													
perator		current state is logo up	• ?			•	micr	o:bit	t sta	rts					
/ariables	0	read ambient brightness				forev	er								
	\bigcirc	read compass orientation						1							
My Blocks		read temperature													
尊		read acceleration x -													
nicro:bit		read magnetic force x •													
Actuator	C) read digital pin P0 •													
		read analog pin P0 +	1												
		set digital pin P0 + outp	n LC	w.											

Figure 3.2.10 "read digital pin"

 When the motion sensor detected that there is people passing by, the servo rotates for 100 degrees; otherwise, it rotates 0 degree. We need "if...then...else" statement here.



3. Run the program:



Figure 3.2.12 Run the Program

Result





Figure 3.2.13 No one passed by Figure 3.2.14 When people passed by

7.Creation of Cat



Project 3: Music Box

1.Story of Cat and Micko



2.Micko' Pocket



1 × micro: bit



1 × micro: bit Expansion Board

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4.Micko's Blackboard

STEP1: connect micro: bit board to computer with USB cable, plug the earphone in the expansion board; connect the motion sensor to pin P1 of the expansion board.





Figure 3.3.1 Connection Diagram

STEP2: Programming

 Drag "pin P0 play sound...until done" block from "micro: bit" module to script area. There are many built-in sounds to choose. We select the sound "dadadadum" here.



Figure 3.3.2 Command "pin P0 play sound...until done"

2. Run the program







 Drag "pin P0 play note-C2 for 1beat" from the "micro: bit" module to script area. Revise the parameter "C2" to play different notes, and change the parameter "1" to adjust the beat.





💿 mic	ro:bit	arts							
💿 pi	n PO		e (Low	C/C	3) be	
💿 pi	n PO		e (Low	C/C	3			
💿 pi	n PO		e (Low	G/C	33) be	
💿 pi	n PO		e (Low	G/C	33) be	
💿 pi	n PO		e (Low	A/A	3) be	
💿 pi	n PO		e (Low	A/A	3) be	
💿 pi	n P0		e	Low	G/C	3 3) be	



Sweetie, writing The Twinkle Start to micro: bit and it can sing!

But Mr. Micko, how could we make micro: bit play music when moving close and stop playing when leaving.

Well, do you still remember the automatic door? The principle of automatic music play is the same as that door. What we need is just a sport sensor.





 Motion sensor has been connected to pin P1, if someone passes near the device, the value of P1 will be 1, otherwise, it will be 0. Therefore, combining it a "if then...else" statement, we can make the smart music box come to life.

• micro:bit	starts				
if 🖉 💿 r	ead digital pi		= 1	then	
💿 pin P	0 🔹 play not	e Low C	CO fo		eat
💿 pin P	0 👻 play not	e Low C	CC3 fo		eat
💿 pin P	0 👻 play not	e Low G	i/G3 fo		peat
e pin P	0 - play not	e Low C	i/G3 fo		peat
e pin P	0 👻 play not	e Low A	/A3 fo		beat
• pin P	0 👻 play not	e Low A	/A3 fo		beat
• pin P	0 👻 play not	e Low G	i/G3 fo		peat

Figure 3.3.7 Run the Program



Project 4: Colorful LED Strip

1.Story of Cat and Micko



2.Micko' Pocket



1 × micro: bit



1 × micro: bit Expansion Board







1 × Sound Sensor 1 × Colorful LED Strip

1 × micro USB Cable



3.Dream of Cat: Turn on the RGB LED strip



4. Micko's Blackboard

STEP1: Connect the LED strip to pin P0 of the expansion board.



Figure 3.4.1 Connection Diagram

STEP2: Add the LED strip command module. Click Expansions->Display->WS2812 RGB LED Strip, then back to the former interface.





Figure 3.4.3 Add the display "WS2812 RGB LED Strip"

STEP3: Programming

1. Click "display" module in the left to present the LED strip commands.



Figure 3.4.4 "WS2812 RGB LED Strip" blocks



There are so many blocks at here. I feel a little dizzy.

Take a breath! Come look at the Little Tip and check the commands one by one.



How to use the commonly used LED strip commands?

To start using the LED strip, we need to select the pin that the LED strip connected to micro: bit, and set up the LED numbers and color modes.

 If you want to set how many LEDs will be used and what brightness they will display, the block is shown below:

pin P2 • 7 RGB lights Brightness 255

(the highest brightness is 255; the LED number is the total number of LEDs that physically included in the strip)

2. If you want to set light effect, you need to use the following block:

m pin P2 • 0 to 4 Leds show gradient color hue: 1 to 360

(LED 0 represents the first LED, and there are 360 colors.)


2. The pin P0 connected to the LED strip comes with 7 LEDs. Set the color range to 01-360 to realize a rainbow effect display (red-green-blue).

Big question! This is because the Arabic numerals are beginning with 0. So we always use 0 as the first one, so the 1 LED

not use 1 to represent 1 LED?

is represented by 0.



Figure 3.4.5 Run the Program



I guess the LED belt has 7 LEDs. Counts the LEDs from 0 to 6: 0,1,2,3,4,5,6. There are 7 numbers at all. So the LED number is from 0 to 6.

Result



Figure 3.4.6 Result

5.Dream of Cat: Turn on the rainbow LEDs



6.Micko's Blackboard

Sweetie, the way to realize this effect is a little harder. You need to think more and be more patient. Fighting!

1. If we want to make the LEDs turn on in a sequence, we need to use a new module: Variables.



To set such a variable, go to: "Variables-> Make a Numeric Variable", and set the name of the variable (to be clear, we named the variable as "the number of LEDs to be lit"). Then click OK.

Blocks Variables New Variable New Variable
Variables New Variable ×
Make a Numeric Variable
Make a Character Variable
Operator Make a List
My Blocks
Mate a Block method
My Bicks Co. minuski stats
Cancel OK
include when button A + pressed
display 🕑 when microbit pin PD+ o
🗊 when logo up -
Figure 3.4.7 Create a new Variable Figure 3.4.8 Name the Variab
R R R R R R R R R R R R R R R R R R R
TIDS
First time to create a variable, let's get to know:
After we created the variable, the blocks of "the name of the variable",
"setto" and "changeby" will appear in the command section:
Blocks
Control
Make a Numeric Variable
Operators
set the number of LEDs to be lit + to ①
Variables change the number of LEDs to be lit - by (1)
Make a Character Variable
My Mala Mala
Blocks Make a List
My blocks
micro:bit Make a Block
lust drag the related block to the script when you need it!

Initialize the pin and total number of the LED, and set the brightness. The initial value of the variable "the number of LEDs to be lit" (α for short) should be set to 0(since all the LEDs are turned off at first).



Figure 3.4.9 Initialize the pin and total number of LEDs

3. When $\alpha < 6$, α LEDs to be lit, then maintain 1 second, and make the parameter getting larger by 1 in every loop. If $\alpha > 6$, make all the LEDs turn

off and start from the beginning. The flow chart below may help us to figure out what the program looks like:





4. Programming according to the flow chart, first setting the conditions, we need to use "if...then...else" and "forever" blocks.



Figure 3.4.11 "if...then...else" and "forever"

5. If "the number of LEDs to be lit"(α) is less than 6, light up α LEDs, wait 1 second, then make the parameter getting larger by 1, which means to make one more LED light up.

micro:bi	it starts																	
TT pin PO	• 7	RGB ligh	ts Brigh	tness	255													
et the num	ber of L	EDs to b	e lit 🔹 to	0														
	1 - 1 1																	
					_													
if < the r	number	of LEDs	to be lit	<= 6	5) th	ien												
if < the r	number P0 •	of LEDs	to be lit	<= (8	5) th EDs to	be lit	Le	ds sh	iow g	jradi	ent c	olor	hue	: 1) to	36	0	
if the r	P0 - Conds	of LEDs	to be lit	er of Ll	5 th EDs to	be li	Le	ds sh	iow ç	jradi	ent c	olor	hue	: 1	to	36	0	
if the r m pin wait 1 s set the n	PO • Po • econds umber o	of LEDs	to be lit ne numb o be lit •	er of L	EDs to	be lit	t) Le	ds sh EDs t	o be	jradi lit	ent o • + 1	olor	hue	: 1 	to to	36	0	
if the r m pin wait 1 s set the n	PO - Conds umber o	of LEDs	to be lit ne numb o be lit •	er of L	5 th EDs to	be lit	t Le	ds sh EDs t	ow g	jradi lit	ent c + 1	olor	hue	: 1 	to to	36	0	
if the r wait 1 s set the nu	PO - Conds econds umber o	of LEDs	to be lit ne numb o be lit •	er of Ll	5 th EDs to	be lit	t Le	eds sh EDs t	o be	yradi lit	ent c		hue	: 1 	to b b b b b b b b b b b b b b b b b b b	36		



 When the number of LEDs to be lit is over 6, set the value of "the number of LEDs to be lit" to 0, and turn off all the LEDs.

micro:bi	it starts														
m pin PO	• 7	RGB lights	Brightness	255											
set the num	ber of L	Ds to be lit	• to 🕕												
forever															
if the r	number o	of LEDs to b	e lit <= (6 the	n 🐑										
TTI pin	P0 -	to the r	umber of	LEDs to h	e lit	Led	s show	v ora	dien	t col	or h	nue: (1	to 🖪	60
					~ "	2000	, 21101	. g					<u> </u>		
wait 1 s	seconds							. 9	,						
wait 1 s set the n	seconds umber o	f LEDs to be	e lit • to (the num	ber c	of LEC) Ds to b	be lit	.) + (1				-	
wait 1 s set the n else	seconds umber o	f LEDs to be	e lit • to (the num	iber c	of LEC)s to t	be lit) + (1	-			-	
wait 1 s set the n else set the n	seconds umber o umber o	f LEDs to be f LEDs to be	e lit • to (the num	iber c	of LEC	os to t	be lit) + () ,	1	-	· ·			
wait 1 s set the n else set the n	econds umber o umber o P0 - cl	f LEDs to be f LEDs to be ear	e lit • to (the num	iber c	of LEC	os to t	be lit	- + (- - -	1	-				
wait 1 s set the n else set the n m pin	seconds umber o umber o PO - cla	f LEDs to be f LEDs to be ear	e lit ▼ to (the num	iber c		os to t	be lit	- + (- - - -	1					







8. Micko's Blackboard

STEP1: The LED strip still connected to P0; connect the sound sensor to pin P1.



Figure 3.4.14 Connection Diagram



Mr. Micko, we have used the sound sensor in the electronic candle!

Smart guy! You are right, the sound sensor used at here was also used in the Page 50. We will also use read analog pin in the micro: bit.



STEP2: Click "micro: bit" module, drag the "read analog pin P0" block to script area, and revise P0 to P1.

E Min	രിക	Project	🛨 Lea	irning	-	Co	onne	ect	dev	/ice	-				
Blocks															
Control		A - butt	on is pre	ssed?											
		P0 - pin	is conne	ected?											
Operators		current sta	te is lo	go up 🗸	?										
Variables	• r	ead ambie	nt bright	tness		1	\odot	mi	сго:	bit s	start	s			
	• r	ead compa	ass orien	tation		÷.	fore	ver							
My Blocks	• r	ead tempe	rature												
	• r	ead accele	ration 🛛												
micro:bit	• r	ead magno	etic force	• x •		6		read	l ana	alog	ı pir	P	0 -		
display		read digita	l pin PC												
display	•• r	ead analog	g pin PO												
Contract (1)	💿 se	et digital pi	in P0 🕶	outpu	t LC	>w	•								

Figure 3.4.15 "read analog pin P0"

STEP3: If the sound value the sensor detected exceeds 40 and the "**the number** of LEDs to be lit" α is less than 6, control the LED strip to light up α LEDs. Then the sensor will be constantly detecting the sound value.



Figure 3.4.16 Flow Chart



Mr. Micko, we have used the sound sensor in the electronic candle!

Smart guy! You are right, the sound sensor used at here is the same as what used in the Page 47. We will also use read analog pin in the micro: bit.



STEP4: Programming

Based on the program of the last project, we need to add a "if...then" statement to judge the sound value. That is to say, when "the number of LEDs to be lit" $\alpha < 6$, if the analog pin P1 is over 40, then α LEDs will be turned on, wait 1 second, change α by 1, and repeatedly to detect if the sound value exceeds 40. When "the number of LEDs to be lit" $\alpha > 6$, all the LEDs will be turned off and start the program from the beginning.



Figure 3.4.17 Run the Programs

9.Creation of Cat

Wow! Such a difficult program! Seems like I need to practice now. How about make a funny sound control light? Come to join me!

	My Design	My Program	

Chapter 4: Become an expert

We have built so many funny works with different types of modules in previous chapters. You may now have a deeper understanding of the micro: bit. Is that enough for the exploration? The answer is doubtlessly NO! Hang on there and we will take another further step into the micro: bit.

Project 1: Electronic Stabilizer

1.Story of Cat and Micko



2.Micko' Pocket



1 × micro: bit



1 × micro: bit Expansion Board



What is gravity?

It is the force that attracts an object toward the center of the earth, or toward any other physical object having mass.

What is acceleration of gravity?

The magnitude of the acceleration due to gravity, denoted with a lower-case g, is 9.8 m/s².

What can we make using acceleration of gravity?

Micro: bit comes with an accelerometer, which can detect the gesture of the micro: bit board automatically. Through the detection of accelerator and programming design, we can realize to make an on-board servo keep pointing upright regardless how we tile the board.



Mr. Micko, will we connect the servo to board and control the servo direction by the acceleration gravity sensor in the board?

Yes, you have understood it. But the acceleration gravity has different directions. Let's turn to the Little Tips to learn which direction we will use.





Micro: bit can detect the gravitational force along X, Y and Z directions, whereas X is along the left-right direction, Y is along the front-back direction, Z is perpendicular to the board and along the updown direction. Show as below:



Figure 4.1.1 X, Y, and Z axes Figure 4.1.2 Value Changing



STEP1: Connect the servo to the pin P0 of micro: bit expansion board.



Figure 4.1.3 Connection Diagram

STEP2: Programming

1. Drag the "read acceleration" block in micro: bit module to script area. It

can be used to get the acceleration of X, Y and Z axes.



Mine	நிற Project 🗕 Learning	•	Con	nect	dev	/ice	•					
Blocks												
Control	stop background playback											
Operators	💽 tempo (bpm)		• for			it st	arts					
	● A button is pressed?											
Variables	P0 • pin is connected?							,				
My Blocks	 read ambient brightness 			reac	, acc	eiera	ation					
	• read compass orientation											
micro:bit	read temperature											
	read acceleration x -											

Figure 4.1.4 "read acceleration"

2. The output value of the accelerometer ranges between -1023 and 1023, and we can use "display" block to check it.

	••• r	nicro:bit	starts						
•									
		display	\bigcirc	read	acce	elera	atio		

Figure 4.1.5 "display" the acceleration value







3. When micro: bit board is titled to the left, a negative output value will be produced along the X direction, so we need the servo to rotate toward right to compensate this angle.



Mr. Micko, is there any connection between the acceleration gravity and servo rotate angle?

Little friend, such a good question. Continue reading the chapters below.



Here we have to use "map" function. Mapping the value of accelerometer's X axis (-1023~1023) onto the degree that the servo rotates (0~180 degree). After mapping, when the board lays flat on the desktop, the angle of the servo will be 90 degrees. The corresponding relations show as Table 4.1.1

Degree of servo	0°	90°	180°
micro: bit accelerometer	-1023	0	1023

Minde Blocks Control bs 🔹 of 🖉 Operators onvert string 123 to Integer 🗸 convert number 🕕 to ASCII Variables convert string a to ASCII My convert number 132 to string Blocks map 0 from[0 , 1023] to[0 , 255 micro:bit constrain 🕕 between(min) 🕕 and(max) 100

Find "map...from...to..." block in "Operators" module.

Figure 4.1.7 "map" block

4. Click Expansions->Actuator->Micro Servo and back to the former interface.



Figure 4.1.8 Servo Module

5. Drag "set pin servo to... degree" block to script area, and put it inside the "forever" block, then nest the "map..." block into it. Shown as below:

orever and a second
🔊 set pin PO 🔹 servo to map 🗰 read acceleration 💉 from: [-1023], 1023] to: [0], 180] deg

Figure 4.1.9 Run the Programs

6. Fix the servo onto the expansion board with double-side adhesive tape so that they both remain relatively still.



Figure 4.1.10 Fix servo and board



Figure 4.1.11 Keep Still



Figure 4.1.12 Tilt to left

5.Invention of Cat



Mr. Micko, I can't believe my eyes, the self-balancing device is so amazing! I found a Compass module in Mind+. Would micro: bit can be a compass?

• read compass orientation

Yes, sweetie, now you can try using the electronic compass in micro: bit and make one compass!



The servo of micro: bit ranges from 0~180°, while the compass need to rotate from 0~360°, so we can directly use "display" and "read compass orientation" to get the position. Read the operation instruction of micro: bit LED panel, then you can make it!

	\bigcirc	My Design	My Program	
)				

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Project 2: DJ panel

1.Story of Cat and Micko



2.Micko' Pocket



1 × micro: bit



1 × micro: bit Expansion Board



1× Knob



1 × micro USB Cable



When switching the knob, the analog value of the pin the knob connected changes from 0~1023. We can divide them into 8 small ranges, corresponding to one octave "Do~Do" and the number of LEDs to be lighted.

The input value of Knob(P1)	Sound	The LED strip
0~128	Do	Light up one LED
128~256	Re	Light up two LEDs
256~384	Mi	Light up three LEDs
384~512	Fa	Light up four LEDs
512~640	So	Light up five LEDs
640~768	La	Light up six LEDs
768~896	Xi	Light up seven LEDs
896~1023	Do'	Light up seven LEDs in blue

Table 4.2.1

4. Micko's Blackboard

STEP1: Connect the knob to Pin P1 of the expansion board, the LED strip to P2.



Figure 4.2.1 Connection Diagram

STEP2: The following logic diagram will help you to build a general idea about how to realize a DJ Bandstand.



Figure 4.2.2 Flow Chart

 Take programming "0<knob P1<128" as an example, set the range of Knob P1 through the "and" function in the "Operators" module, then put the set range into the condition of "if...then...else" block, nest the LED strip and sound effect blocks inside the "...then..." function, and add a "wait 1 second" block. Show as below. The rest 6 programs are similar to this one.



Figure 4.2.3 Sample Program 1

2. Since there are only 7 LEDs, so we can use different light effect to express the sound "Do" in the eighth section as shown below.





Figure 4.2.5 Run the Program

3. To convenient operation, we can make a little bit improvement, such as add a handle to the knob, or mark the range of each sound.



Figure 4.2.7 Improvement 1



Figure 4.2.8 Improvement

5.Invention of Cat

Mr. Micko, I am so exciting to make my own DJ bandstand.

My dear, do you want to improve your DJ bandstand? Try using the 5 x 5 LED dot-matrix in micro: bit to display notes!



\bigcirc	My Design	My Program	

Project 3: Automatic Door

1.Story of Cat and Micko



Ha, ha, let's make it!



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2.Micko' Pocket



2× micro: bit



1 × LED Module



1 × Motion Sensor



2× micro: bit Expansion Board



1 × Push Button



2× micro USB Cable



Micko



Mr. Micko, why should we use 2 boards now?

Well, we need to use these two boards to imitate remote doorbell. We will put one of them into outside, which is equals to doorbell. This is the server. And we will put the other one into your room to receive the signals from the server. That is the client. So you can know the outdoor even you are staying your bedroom.



Mr. Micko, what should we connect between the server and the client?

At this time, we need to apply the knowledge in the flash LED, the notification light and the automatic door. Let's come to the Little Tips to check what should be connected!





4. Micko's Blackboard

STEP1:

Hardware connection of micro: bit transmitter.



Figure 4.3.1 Transmitter End

Hardware connection of micro: bit receiver



Figure 4.3.2 Receiver End

STEP2: Get to know about wireless transmission module



Mr. Micko, How could we send the signal if someone knock the doorbell from the server?

Here we need to learn a new thing: wireless transport module. When the server receives the signals from users, it will pass the signals to the client. So we need to program the server and the client separately.





STEP3: Program the transmitter

1. The following flow chart can give us a roughly idea of how to write the program.







2. Programming according to the flow chart.



Figure 4.3.4 Transmitter Programs

STEP4: Program the receiver

1. Draw the flow chart, design the receiver programs.



Figure 4.3.5 Receiver Flow Chart

Little friend, here we also need to open the wireless communication module before programming and set the wireless program, and execute the program when the client receives the wireless signals.



2. Programming according to the flow chart.



Figure 4.3.6 Receiver Program

Sweetie, please do not forget "0","1","2" when reading the signal(please remember the string we read should go with "").



Result

1. When there is someone passing by but not ringing the bell:



Figure 4.3.7 Result 1

2. When there is someone ringing the bell





5.Invention of Cat

Sweetie, please do not forget "0","1","2" when reading the signal(please remember the string we read should go with "")





Project4: The Bomb Escape

1.Story of Cat and Micko



2.Micko' Pocket



1 × micro: bit



1 × micro: bit Expansion Board



1 × micro USB Cable

1 × Colorful LED Strip

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3.Dream of Cat

When we start play the game Bomb, the LEDs also enter the countdown mode at the time. When all LEDs are OFF, which means the countdown is over. The bomb will explode imminently.

If we went to disposal the bomb, we need to lean the micro: bit to the directions that LEDs show.

The explosive ordnance disposal device includes following three parts :

1. Action Recognition: identify if the tilt direction of the micro: bit board is same to the direction its LEDs pointed.

LED Strip Countdown: set countdown light effect to the LED strip, turn off
 LED every 10 seconds.

3. Score System: if the 20 actions are finished before all the LEDs of LED strip go out, you win; otherwise, game over.

4. Micko's Blackboard

STEP1: Connect the colorful LED strip to pin P0 of the expansion board.



Figure 4.4.1 Connection Diagram

STEP2: Action Recognition

1. Learn the related commands

Firstly, we need the micro: bit board to generate and display a direction randomly, then tilt the board, if the direction the board tilts to is same to the displayed direction, generate a new random direction, if not, micro: bit LEDs panel keeps displaying the current direction. The flow chart is shown as below:



Figure 4.4.2 Action Recognition Flow Chart



Select a random number:

Use the "pick random...to..." function in "Operators" module to select the number in a certain range. Since there are four directions (up, down, left and right), we can use number 0~3 to represent four target directions respectively.



Construct functions:

Use the "make a block" in "My blocks" module to construct a function. When it is constructed, drag the block to script area if we need it.

Now we need to make the four numbers "0, 1, 2, 3" correspond to the four directions "up, down, left and right". We can make a "generate a random direction" block. The constructed block will appear in the left.





- 2. Programming
- Create a variable "target direction" to represent the arrow's direction on micro: bit LED panel, set the variable value to "pick random 0 to 3"



2) Create a function "generate a random direction", and make the four numbers "0, 1, 2, 3" correspond to the four directions of the arrow displayed on the LED panel.



Figure 4.4.4 "generate a random direction" function

3) Make a variable "operation direction" to represent the current direction the board tilts, and use it with "current gesture" to make the four "operation direction" correspond to the four numbers.



Figure 4.4.5 Get the current gesture

 Here we need to use a "if...then...else". If the operation direction is same to the target direction, then continue to generate a new random direction.

if target direction = operation direction then													
set	set target direction - to pick random 1 to 3												
set) + (1							
												1	
gene	rate a	rand	lom di	rectio	n -								

Figure 4.4.6 if...then...else

5) The whole program of this part is shown below:



Figure 4.4.7 Programs of action recognition
STEP3: LED Strip Countdown

1. Draw a program flow chart

The LEDs on the LED strip will go off one by one as the time goes by. The faster you react; the more LEDs keep on at last.



Figure 4.4.8 LED strip countdown flow chart

2. Programming

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1) Create variables "time" and "the number of LEDs", set "time" to 0, and set "the number of LEDs" to 7 (means 7 LEDs keep on). Combine them with

"if...then...else" to write the programs as the flow chart.

Note: micro: bit needs extra time to process the data, so the clock will run a bit slower than we set.



Figure 4.4.9 "if...then...else"

2) Remember to set the LED's lighting effect:



Figure 4.4.10 LED Lighting Effect

3) The whole programs of the last two parts:



Figure 4.4.11 Whole programs of the last two parts



No problem, if you want to shorten the countdown time, try set the time to 5s or 1s.



STEP4: Score System

1. Draw the flow chart

If the operation direction is same as the target direction, then we get 1 point. If the number of LEDs (keep on) is over 0 when we got 20 points, we are the winner, the final score is the number of LEDs (keep on). Otherwise, we failed.

Here is the flow chart:



Figure 4.4.12 Flow chart of score system

- 2. Programming
- Create variables "points" and "score", set them to 0. Combine them with "if...then...else" function to meet the requirements of the flow chart.



Figure 4.4.13 Part of the Program



My sweetie, do you remember? The LEDs are counted from 0. So the number of LEDs turn ON in reality is just 1 more than the number in



2) The final program is shown as below:



5.Invention of Cat





Mr. Micko, micro: bit and Mind+ are so interesting! They are so powerful!

My little friend, what we played is just the tip of the iceberg. There are so many functions in micro: bit and Mind+, and they are waiting for your exploration.





Mr. Micko, thanks for all your help all this time. I will explore it with enthusiasm as always. But where could I find you and ask you my problems?

Do not worry, I am always with you on line. If you got any problems and any good ideas to share, come to visit the

DFRobot Community: www.dfrobot.com

In this community, you can find many makers like you. Wish DFRobot community can record your growth.





Wow! So wonderful! Mr. Micko, see you in the DFRobot community, wishing I could find more friends in the community.

