

SECRET

SIMPLE ROBOTICS
FIELD MANUAL

Strategic Robotic Services
(Provisional)

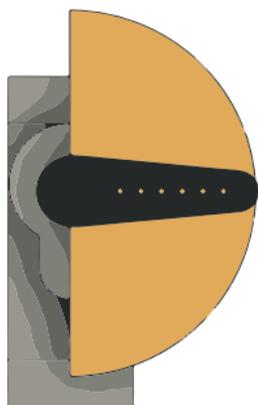
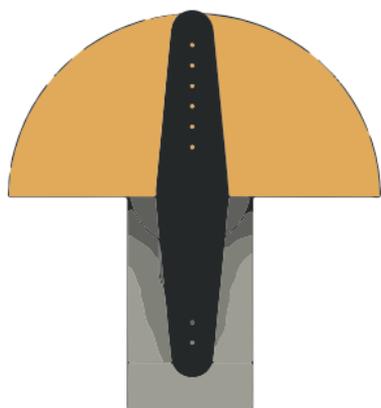
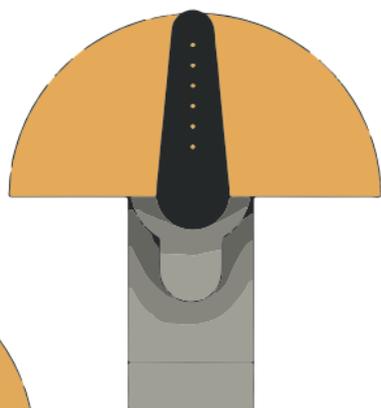
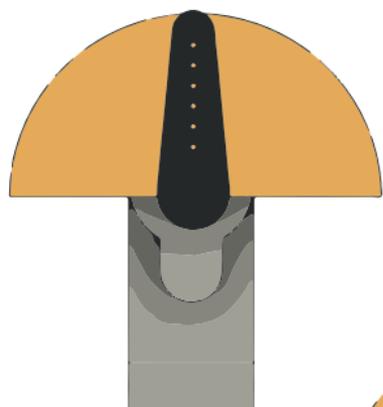


OSHWA UID
UK000047



Prepared under the direction of
The Director of Strategic Robotic Services

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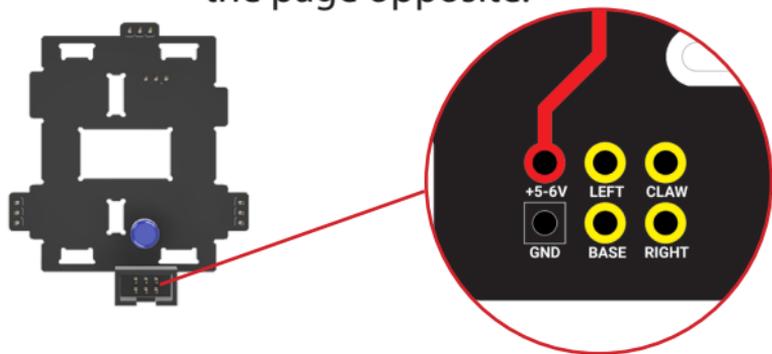
Important Notes:

Before assembly you will need to test and calibrate your servo motors to the positions shown overleaf.

The process differs depending on your choice of control board. Please head to <https://shop.mearm.com/build> and select the correct product.

If you do not calibrate your servo motors now you will need to dismantle parts of your MeArm later on.

Do not skip ahead. Calibrate your servos so they are able to move in the arcs shown on the page opposite.



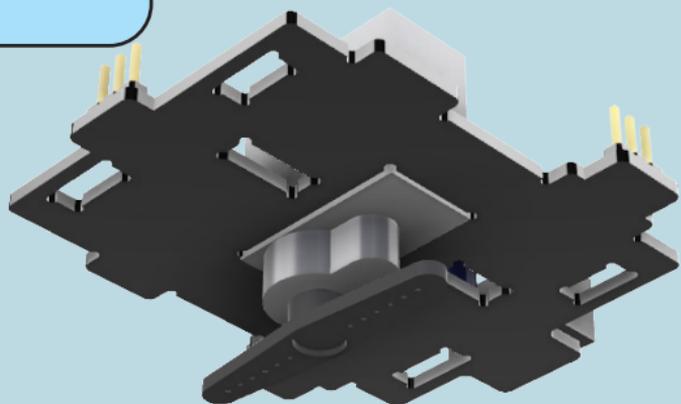
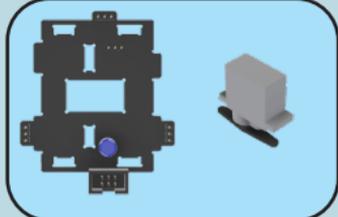
The MeArm project started in 2014, with the aim of making a robot arm that was made from a small number of components, was easy to assemble, and fun to use. The design files were shared online and the first viral robot arm was born. This latest version is the product of thousands of hours of open source development, from all around the globe.

We hope you will enjoy the product you have purchased, and we thank you for your support and feedback.

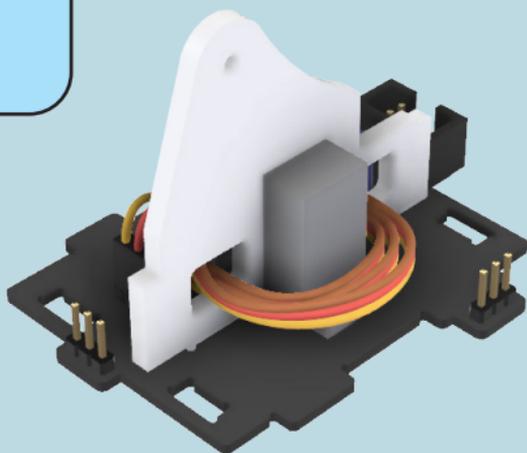
Remember:

- Joints should move freely. Without the servo motors fitted the robot should be a like a resting marionette.
- Parts should sit in place with very little or no force. It may be that you can rotate a part to get it to fit.

#1



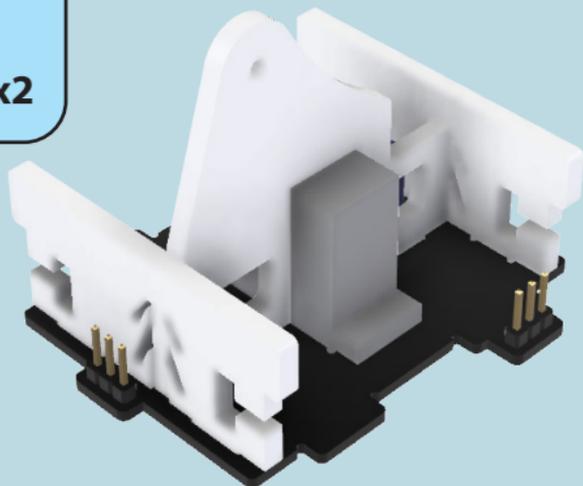
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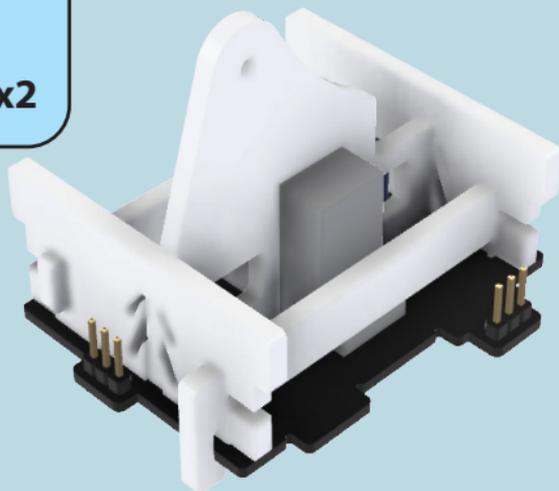
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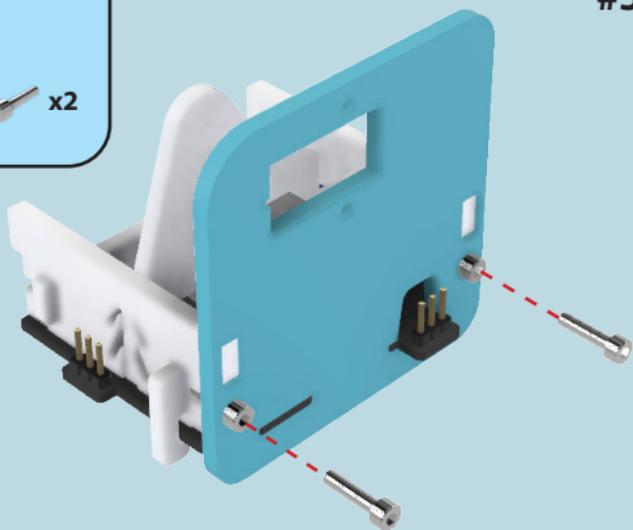
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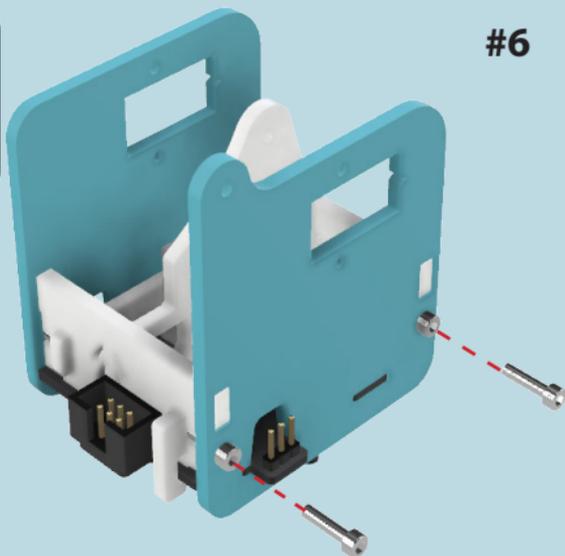
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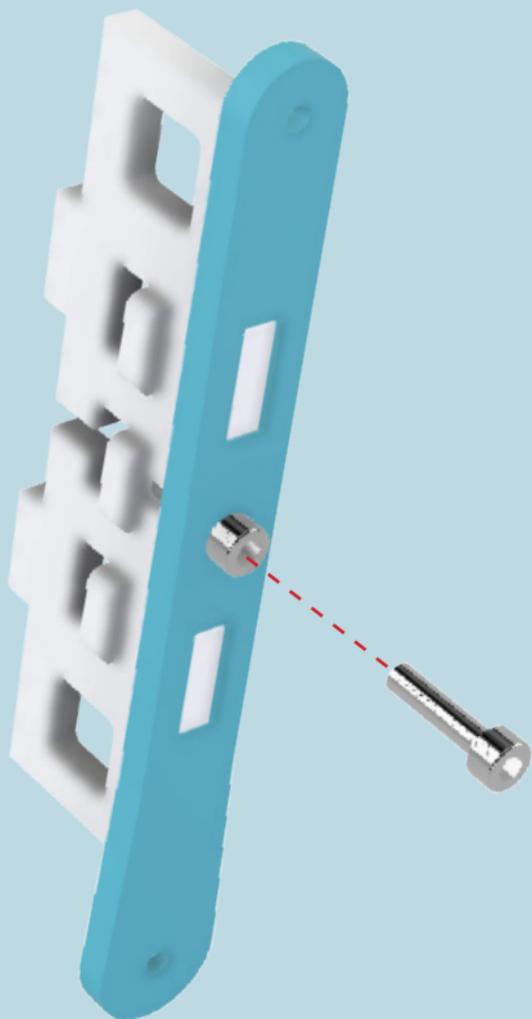
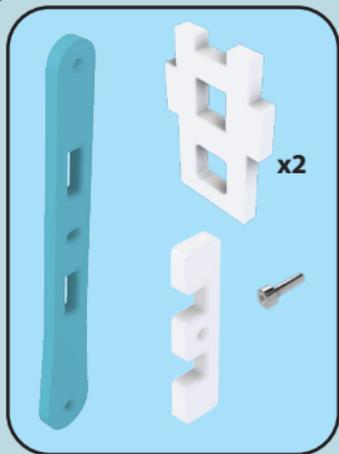
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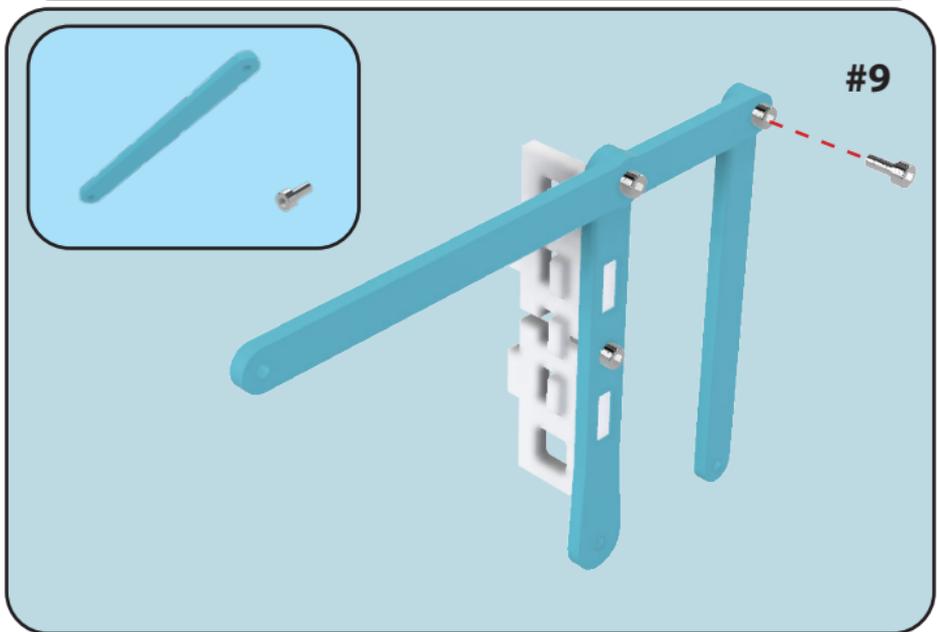
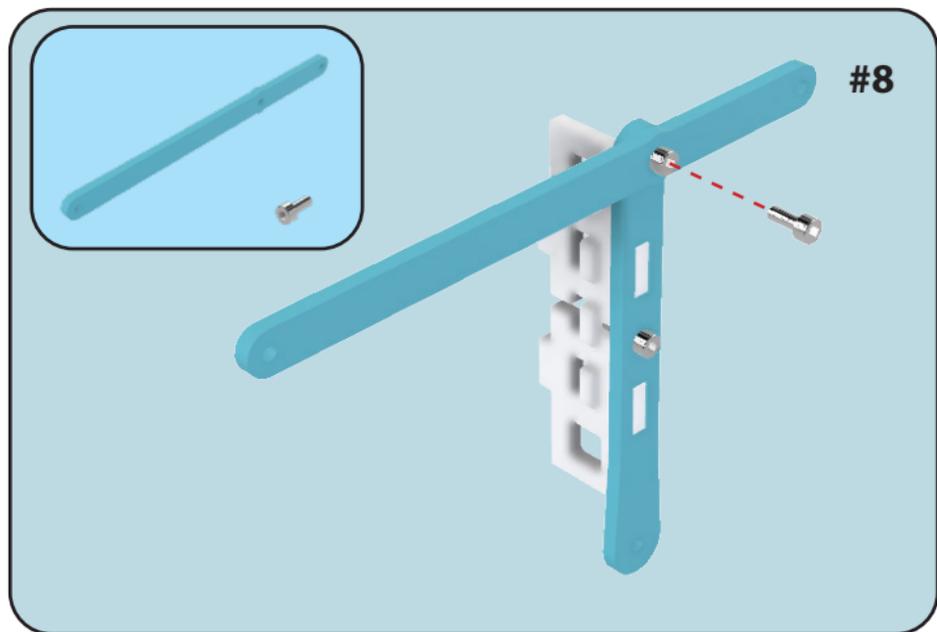


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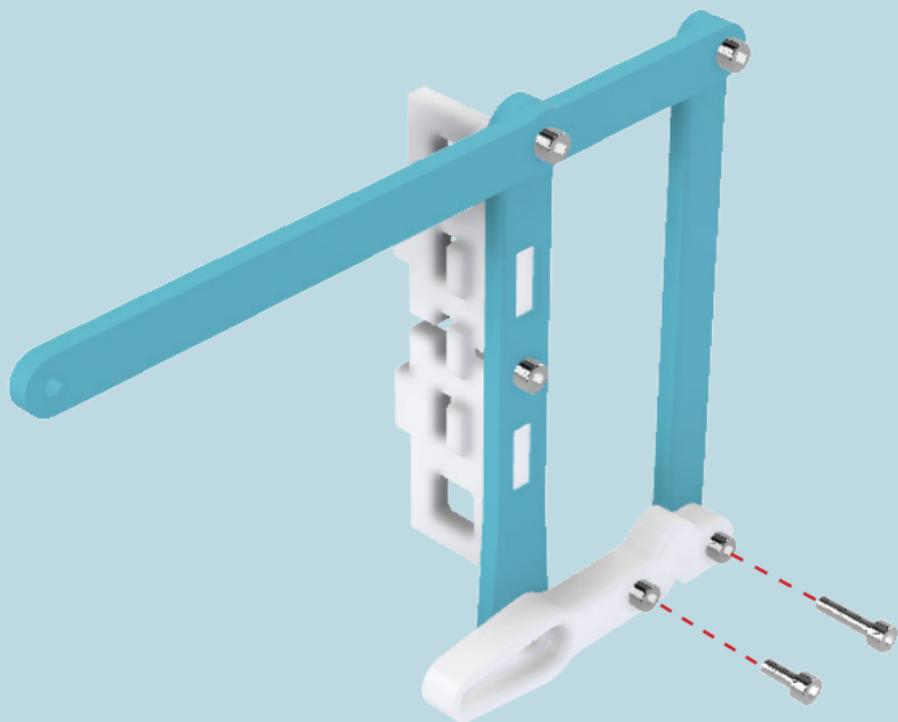


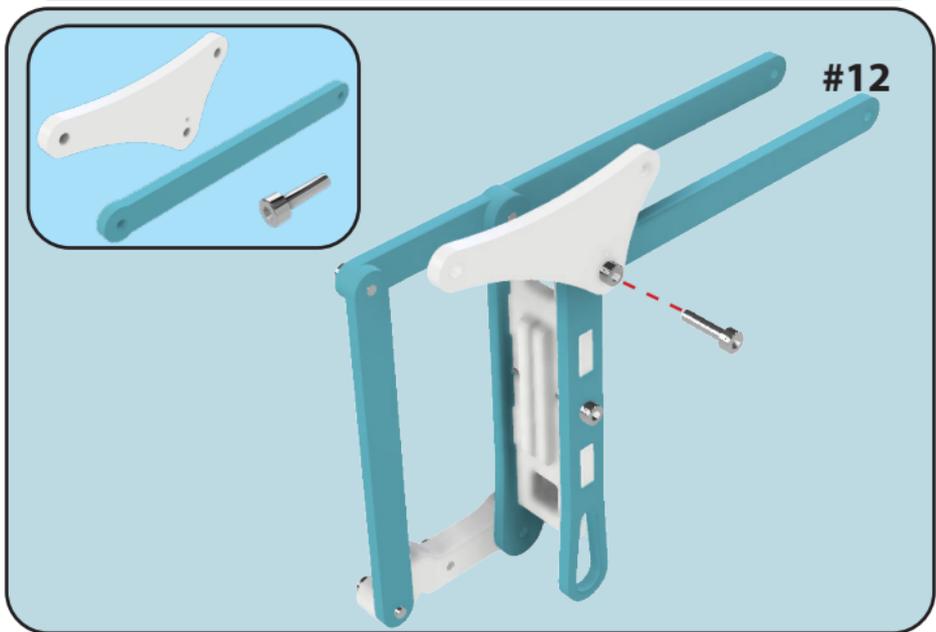
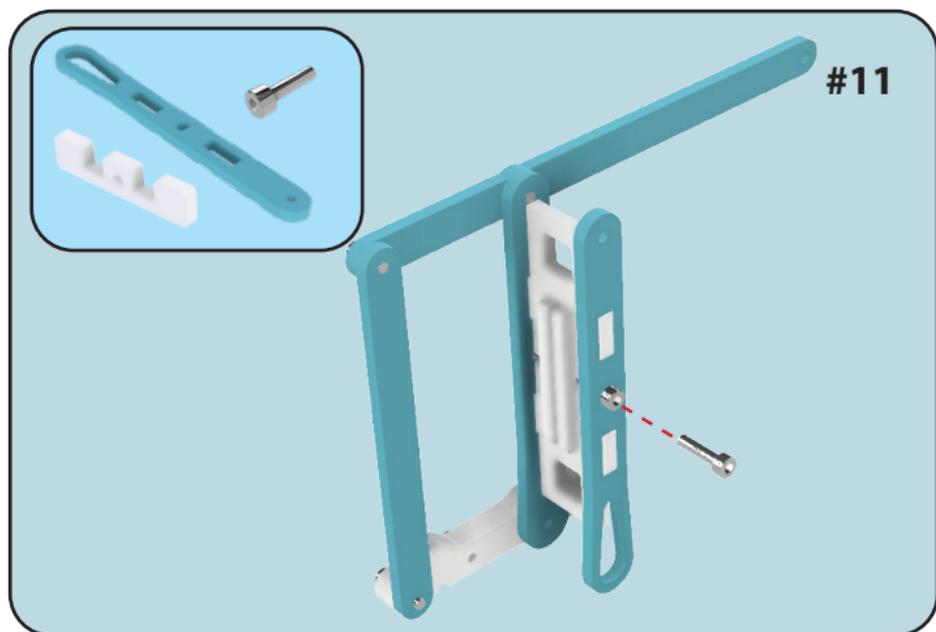
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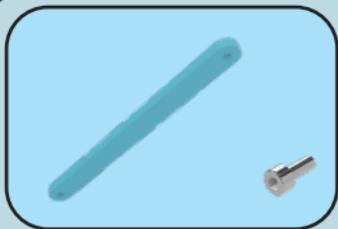


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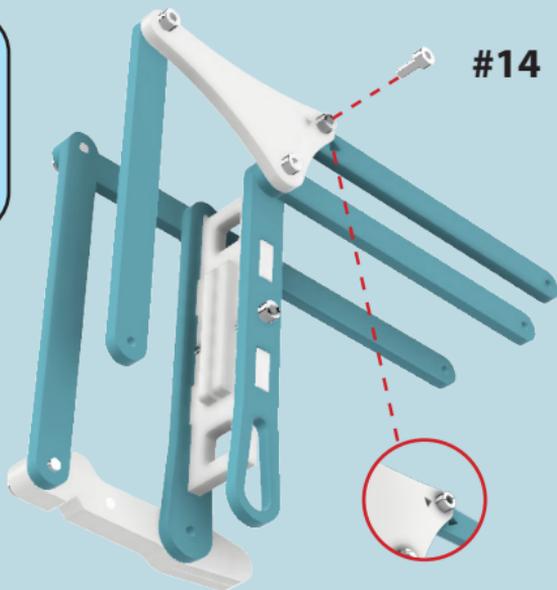
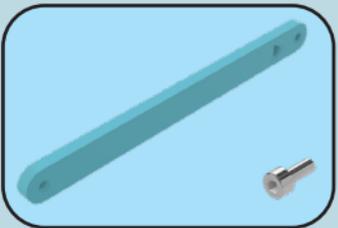




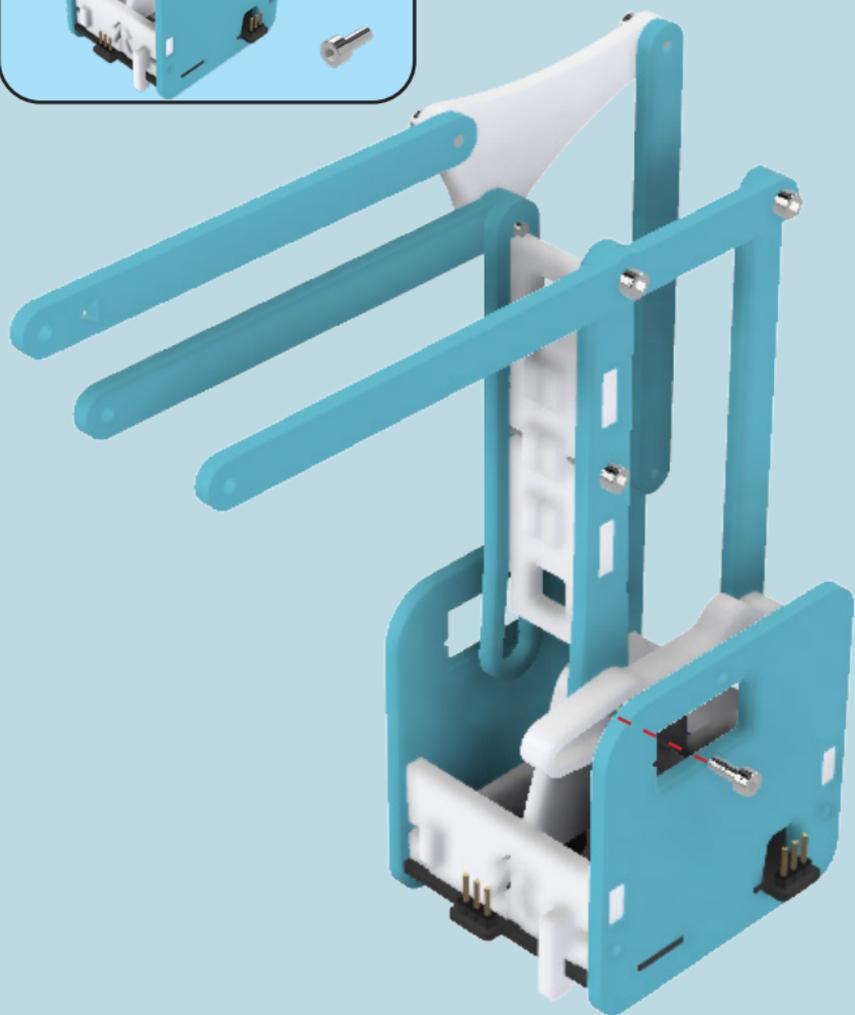
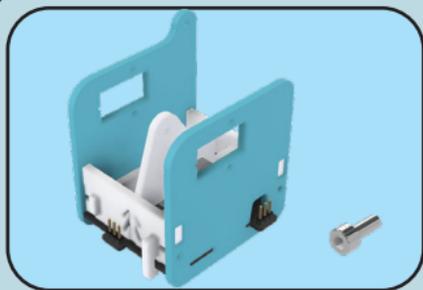
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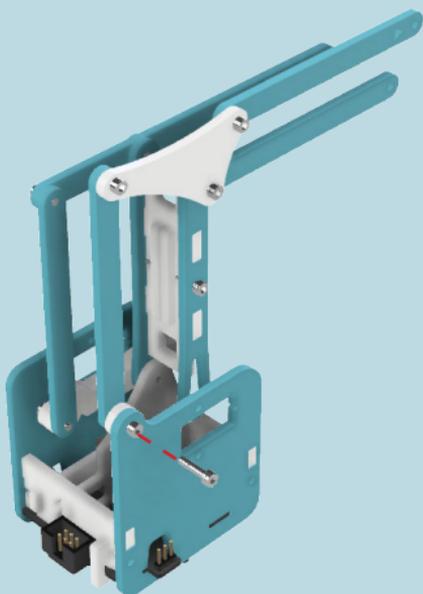
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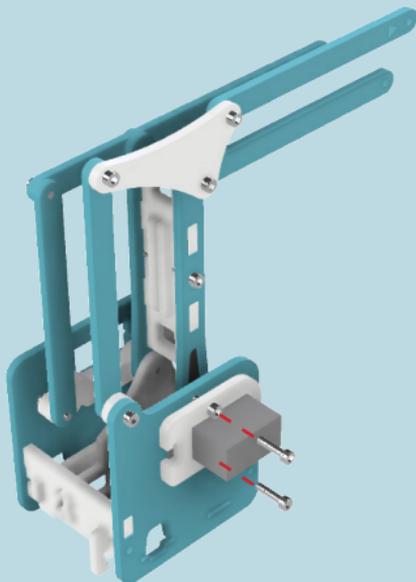
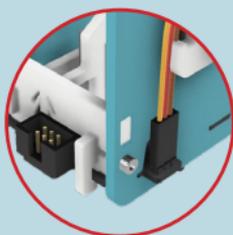
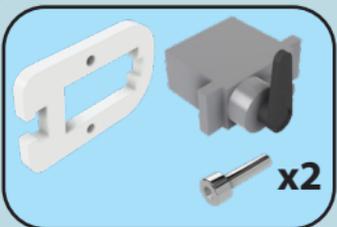
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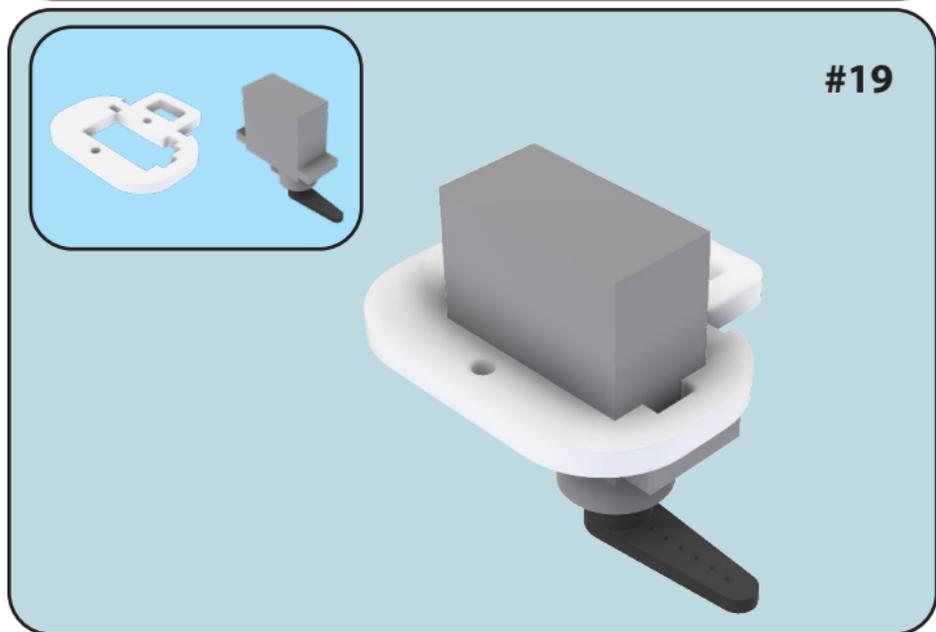
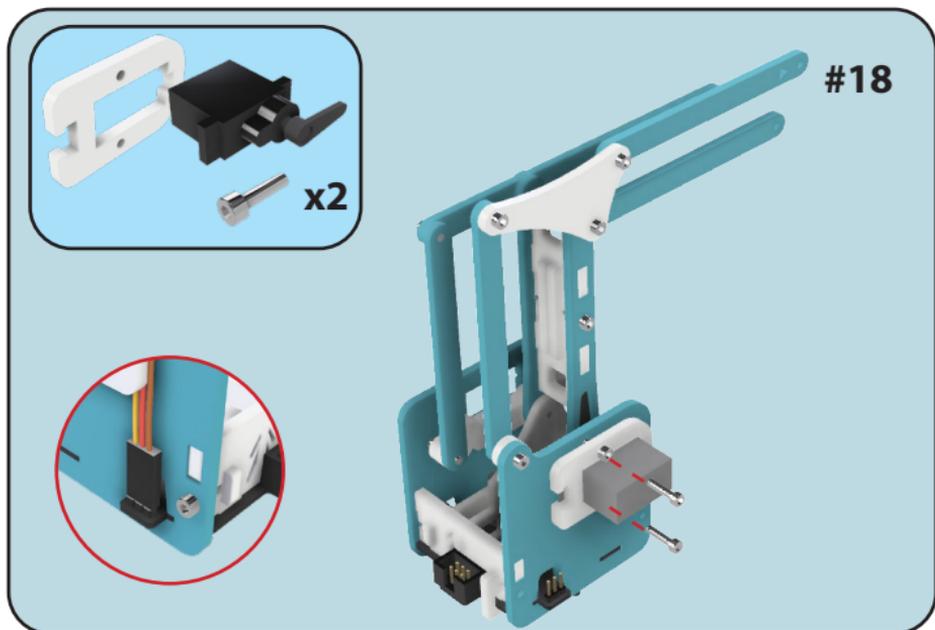


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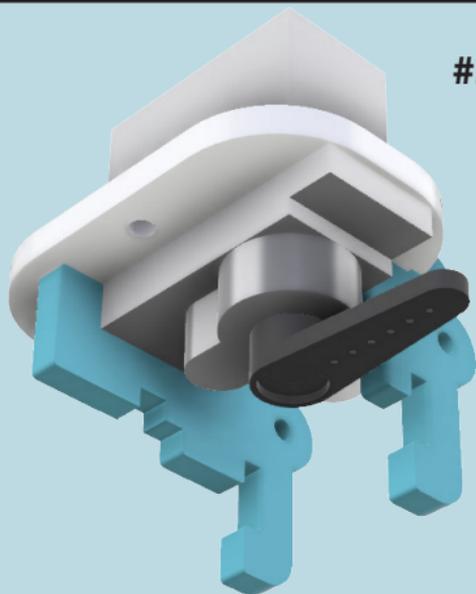
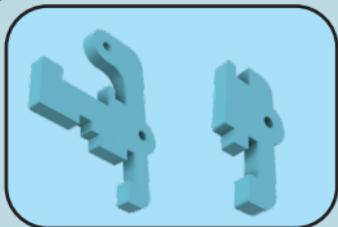


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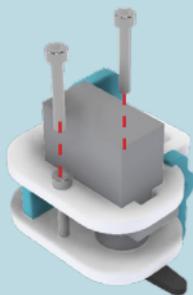
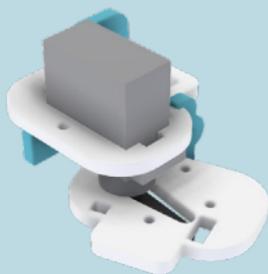
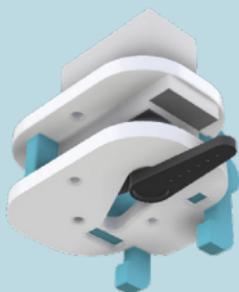
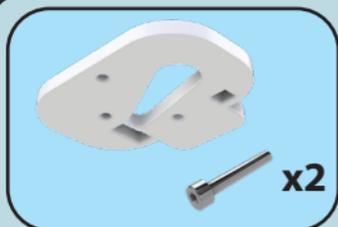




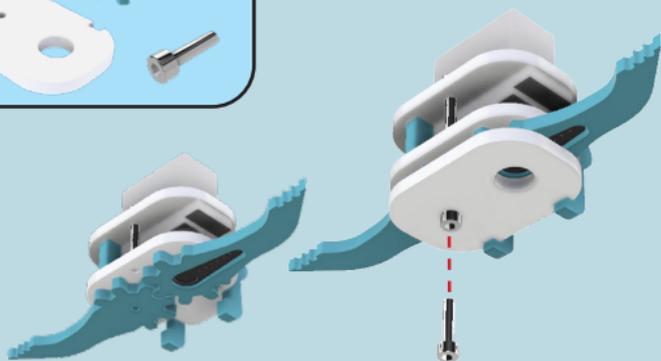
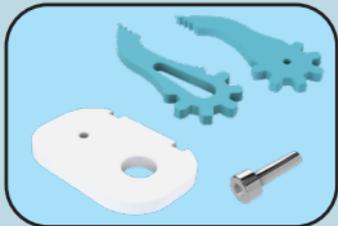
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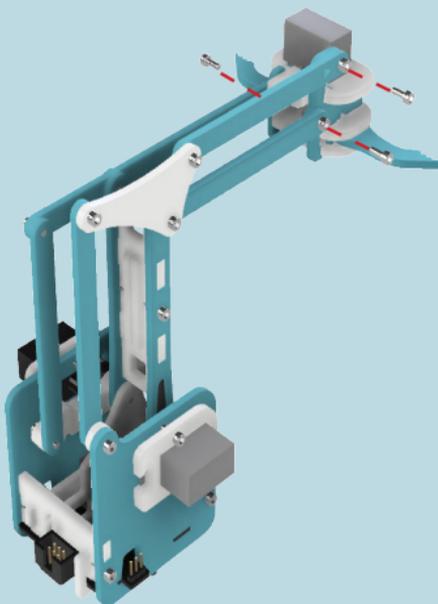
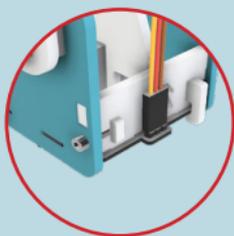
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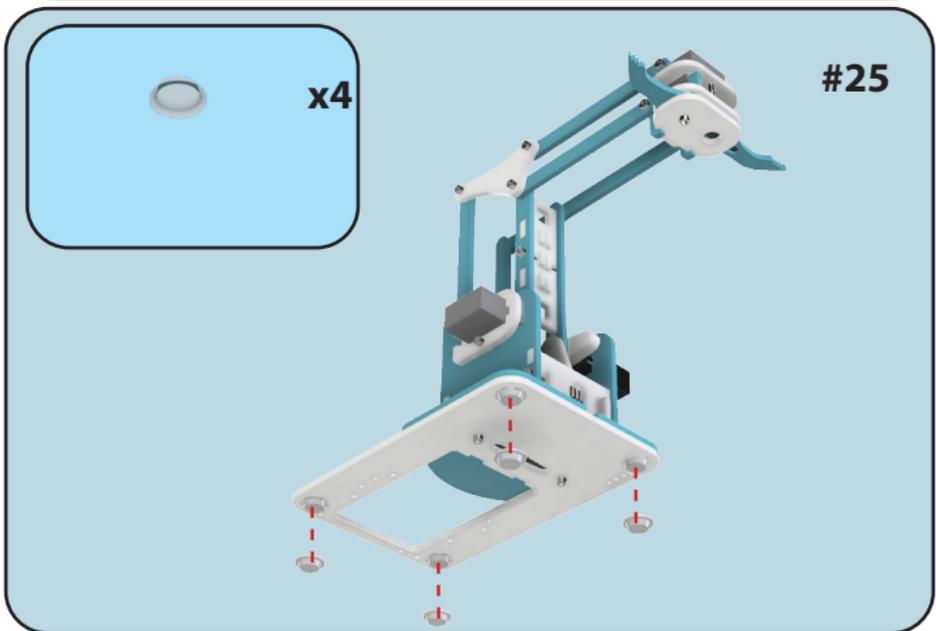
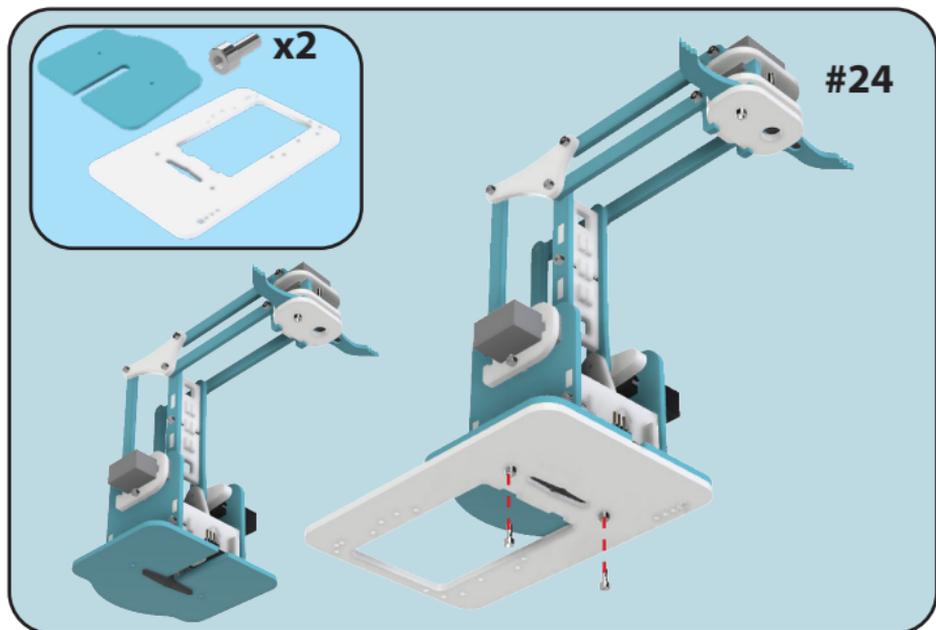


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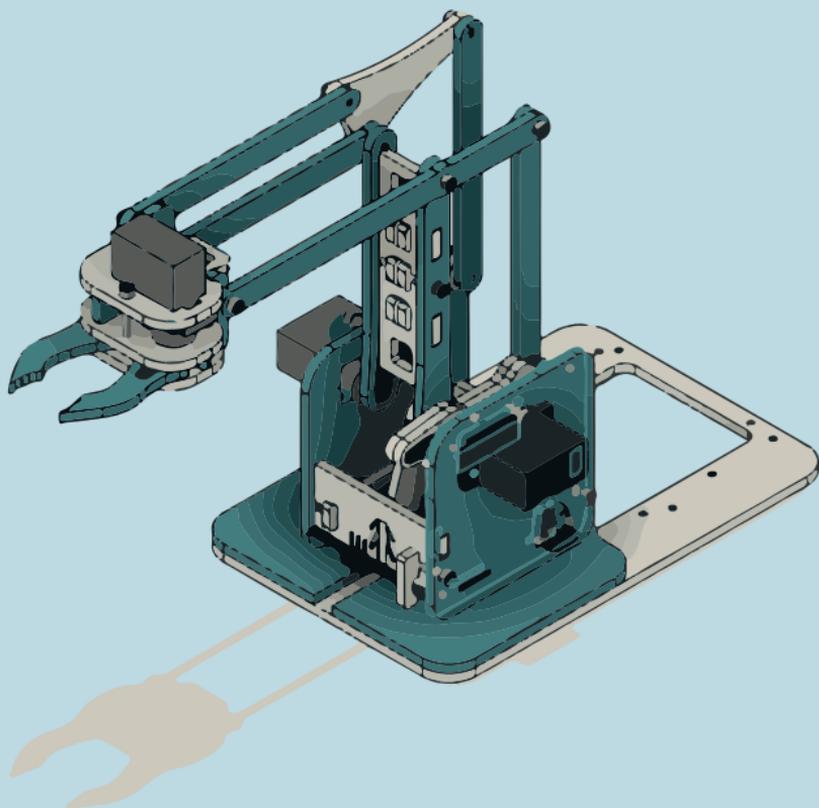




Congratulations!
Build Complete.
Happy Coding!

See mearm.com/build
for more information

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